

nag_complex_lu_solve_mult_rhs (f04akc)

1. Purpose

nag_complex_lu_solve_mult_rhs (f04akc) calculates the approximate solution of a set of complex linear equations with multiple right-hand sides $AX = B$, where A has been factorized by nag_complex_lu (f03ahc).

2. Specification

```
#include <nag.h>
#include <nagf04.h>

void nag_complex_lin_eqn_mult_rhs(Integer n, Integer nrhs, Complex a[],
    Integer tda, Integer pivot[], Complex b[], Integer tdb, NagError *fail)
```

3. Description

To solve a set of complex linear equations $AX = B$, the function must be preceded by a call to nag_complex_lu (f03ahc) which computes an LU factorization of A with partial pivoting, $PA = LU$, where P is a permutation matrix, L is lower triangular and U is unit upper triangular. The columns x of the solution X are found by forward and backward substitution in $Ly = Pb$ and $Ux = y$, where b is a column of the right-hand side.

4. Parameters

n

Input: n , the order of the matrix A .
 Constraint: $\mathbf{n} \geq 1$.

rhs

Input: r , the number of right-hand sides.
 Constraint: $\mathbf{nrhs} \geq 1$.

a[n][tda]

Input: details of the LU factorization, as returned by nag_complex_lu (f03ahc).

tda

Input: the second dimension of the array **a** as declared in the function from which nag_complex_lu_solve_mult_rhs is called.
 Constraint: $\mathbf{tda} \geq \mathbf{n}$.

pivot[n]

Input: details of the row interchanges as returned by nag_complex_lu (f03ahc).

b[n][tdb]

Input: the n by r right-hand side matrix B .
 Output: B is overwritten by the solution matrix X .

tdb

Input: the second dimension of the array **b** as declared in the function from which nag_complex_lu_solve_mult_rhs is called.
 Constraint: $\mathbf{tdb} \geq \mathbf{nrhs}$.

fail

The NAG error parameter, see the Essential Introduction to the NAG C Library.

5. Error Indications and Warnings

NE_INT_ARG_LT

On entry, \mathbf{n} must not be less than 1: $\mathbf{n} = \langle \text{value} \rangle$.
 On entry, \mathbf{nrhs} must not be less than 1: $\mathbf{nrhs} = \langle \text{value} \rangle$.

NE_2_INT_ARG_LT

On entry, **tda** = $\langle\text{value}\rangle$ while **n** = $\langle\text{value}\rangle$. These parameters must satisfy **tda** \geq **n**.

On entry, **tdb** = $\langle\text{value}\rangle$ while **nrhs** = $\langle\text{value}\rangle$. These parameters must satisfy **tdb** \geq **nrhs**.

6. Further Comments

The time taken by the function is approximately proportional to n^2r .

6.1. Accuracy

The accuracy of the computed solution depends on the conditioning of the original matrix. For a detailed error analysis see Wilkinson and Reinsch (1971) p 106.

6.2. References

Wilkinson J H and Reinsch C (1971) *Handbook for Automatic Computation (Vol II, Linear Algebra)*
Springer-Verlag pp 93–110.

7. See Also

nag_complex_lu (f03ahc)
nag_complex_lin_eqn_mult_rhs (f04adc)

8. Example

To solve the set of linear equations $AX = B$ where

$$A = \begin{pmatrix} 1 & 1 + 2i & 2 + 10i \\ 1 + i & 3i & -5 + 14i \\ 1 + i & 5i & -8 + 20i \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$

8.1. Program Text

```
/* nag_complex_lu_solve_mult_rhs(f04akc) Example Program
 *
 * Copyright 1990 Numerical Algorithms Group.
 *
 * Mark 1A revised, (Oct 1990).
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdl�.h>
#include <nagf03.h>
#include <nagf04.h>

#define NMAX 5
#define TDA NMAX
#define TDB NMAX

main()
{
    Complex det;
    Complex a[NMAX][TDA], b[NMAX][TDB];
    Integer i, j, n, dete, nrhs = 1;
    Integer pivot[NMAX];
    static NagError fail;

    fail.print = TRUE;
    Vprintf("f04akc Example Program Results\n");

```

```

Vscanf("%*[^\n]"); /* Skip heading in data file */
Vscanf("%ld",&n);
if (n > 0 && n <= NMAX)
{
    for (i = 0; i < n; i++)
        for (j = 0; j < n; j++)
            Vscanf(" (%lf , %lf ) ", &a[i][j].re, &a[i][j].im);
    for (i = 0; i < n; i++)
        for (j = 0; j < nrhs; j++)
            Vscanf(" (%lf , %lf ) ", &b[i][j].re, &b[i][j].im);
    f03ahc(n, (Complex *)a, (Integer)TDA, pivot, &det, &dete, &fail);
    if (fail.code!=NE_NOERROR)
        exit(EXIT_FAILURE);
    else
    {
        f04akc(n, nrhs, (Complex *)a, (Integer)TDA, pivot,
                (Complex *)b, (Integer)TDB, &fail);
        if (fail.code!=NE_NOERROR)
            exit(EXIT_FAILURE);
        Vprintf("Solution\n");
        for (i=0; i<n; i++)
        {
            for (j=0; j<nrhs; j++)
                Vprintf("(%7.3f, %7.3f) ", b[i][j].re, b[i][j].im);
            Vprintf("\n");
        }
    }
}
else
{
    Vfprintf(stderr, "Error: n is out of range: n = %3ld\n", n);
    exit(EXIT_FAILURE);
}
exit(EXIT_SUCCESS);
}

```

8.2. Program Data

```

f04akc Example Program Data
3
( 1.0, 0.0 ) ( 1.0, 2.0 ) ( 2.0,10.0 )
( 1.0, 1.0 ) ( 0.0, 3.0 ) (-5.0,14.0 )
( 1.0, 1.0 ) ( 0.0, 5.0 ) (-8.0,20.0 )
( 1.0, 0.0 ) ( 0.0, 0.0 ) ( 0.0, 0.0 )

```

8.3. Program Results

```

f04akc Example Program Results
Solution
( 10.000,   1.000)
(  9.000,  -3.000)
( -2.000,   2.000)

```
